

Fig. 1

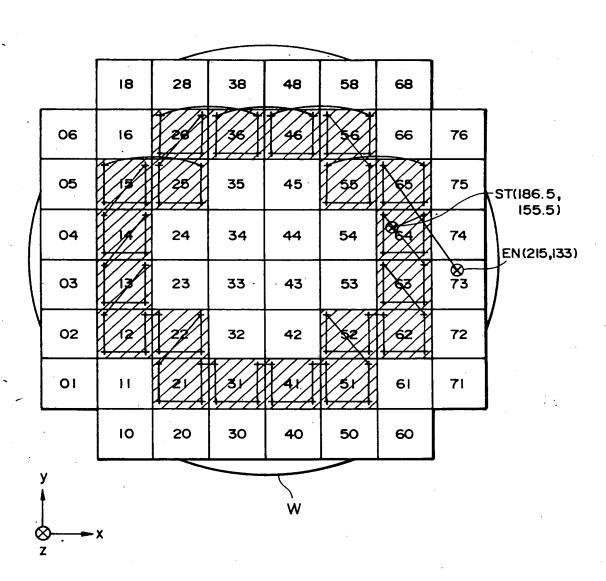
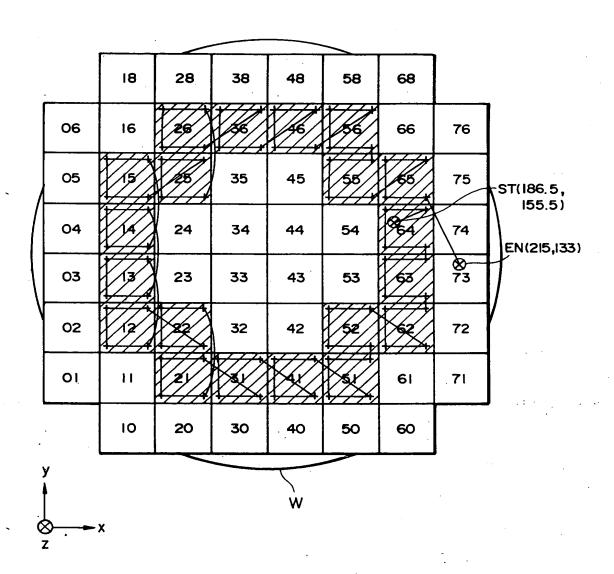


Fig.2



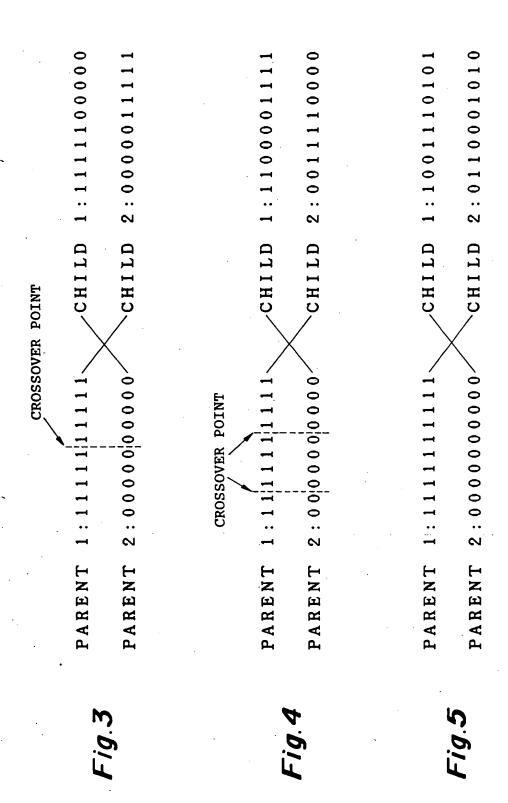


Fig.6

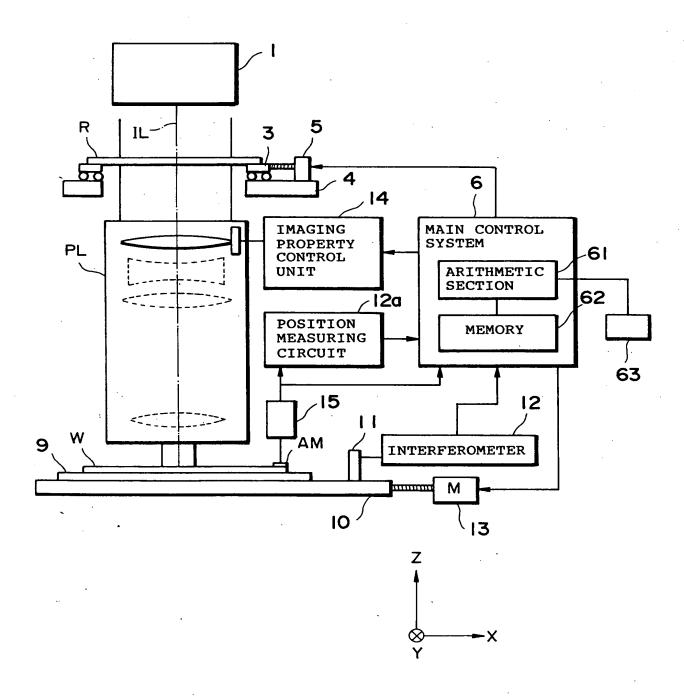


Fig.7

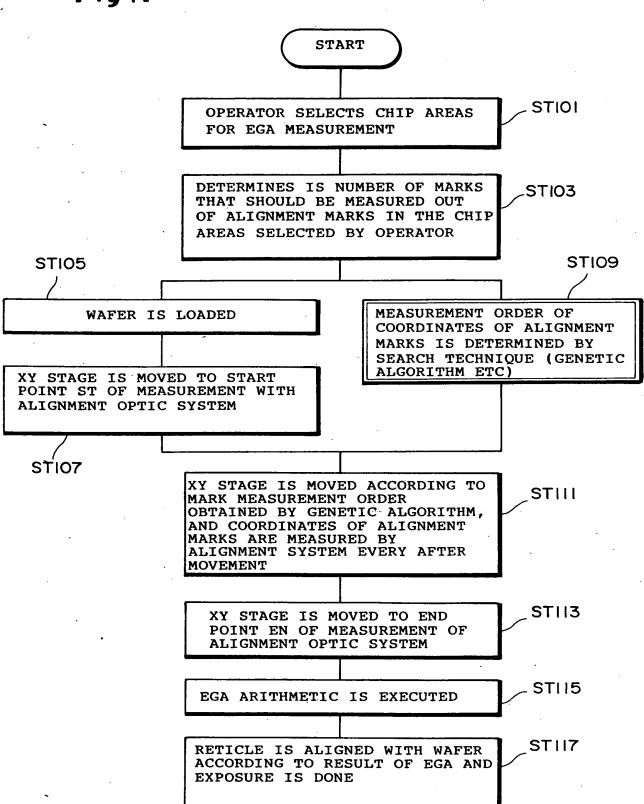




Fig.8

ATTRIBUTE		VALUE OF PARAMETER SET IN EMBODIMENT
START POINT ST	X Y	186.5 (mm) 155.5 (mm)
END POINT EN	X Y	215 (mm) 133 (mm)
ACCELERATION OF WAFER STAGE 10	X Y	0.34g 0.2g
MAX SPEED OF WAFER STAGE 10	X Y	270 (mm/sec) 200 (mm/sec)
SETTLING TIME OF WA	AFER STAGE	0.032 (sec)
TIME NECESSARY FOR COORDINATES OF ONE MARK		0.5 (sec)

g:ACCELERATION OF GRAVITY (=9.80m/sec)

Fig.9

CHIP AREA	COORDINATES OF CENTER	CHIP AREA	COORDINATES OF CENTER
12	(83, 105)	4 1	(149, 83)
1 3	(83, 127)	4 6	(149, 193)
1 4	(83, 149)	5 1	(171, 83)
1 5	(83, 171)	5 2	(171, 105)
21 .	(105, 83)	5 5	(171, 171)
22	(105, 105)	5 6	(171, 193)
2 5	(105, 171)	6 2	(193, 105)
2 6	(105, 193)	6 3	(193, 127)
3 1	(127, 83)	6 4	(193, 149)
3 6	(127, 193)	6 5	(193, 171)



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 								į			. :		: :	:			(UNIT: SEC		65(4)	0.439407	0.513481	[0.513481]	0.439407	0.439407	0.513481		0110		-10		0.109449	×	0.172
(2)	0.142	0.142	0.242	0.242	109449				439407	513481	.513481	439407	0.439407	0.513481	0.557926				65(3)	0.365333	0.439407	0.439407	0.365333	0.365333	0.439407		671 0 1	0 149	0 132981		×	0.109449	0.172
1) [13(2)	0.142	0.142	0.242	0.242	0	109449 X		•	365333 0.		0	0	$0.365333 \mid 0.$	_	$0.483852 \mid 0.$				65(2)	0.365333	0.439407	0.462	0.462	[0.365333]	0.439407		676 0	247.0 740.0	0 109449	וי	0, 132981	!	0.272
(4) 13(1)	132981	132981	109449		0.242 ×	0.242 0.			0.	439407 0.	0.	_	$0.365333 \mid 0.$	439407	0.483852 0.				65(1)	0.439307	0.513481	0.513481	0.462	0.439407	[0.513481]	••••	676 0 1	0.00	7.77	0 109449	0.132981	<u> </u>	0.272
12	132981 0.	132981 0.	0	109449 ×	0.242	0.242			439407 0.	0	0%543481		0						64(4)	0.439407	0.513481	0.513481	0.439407	0.439407	0.513481		0 100440	- 1	0 0			0.142	0.091992
2) 12(3)	109449 0.	0	132981 ×	132981 0.			•••		439407 0.				E	513481 0.	557926	-և			64(3)	0.365333	0.439407	0.439407	0.365333	0.365333	0.439407		2	0 100440	0.103443	0.642	071.0	٠l ٠	0.150519
1) 12(2)	0	109449 X	-					•	0.36533 0.	0	-	36533 0	36533 0	-	0							:					:			!			!
TART 12(1)	378296 X	0.45237 0.	0.45237 0.	378296 0	╀	0.45237			123721 0			0.1595 0	4955	10	-		L		<u> </u>										-:				

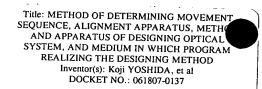


Fig.11

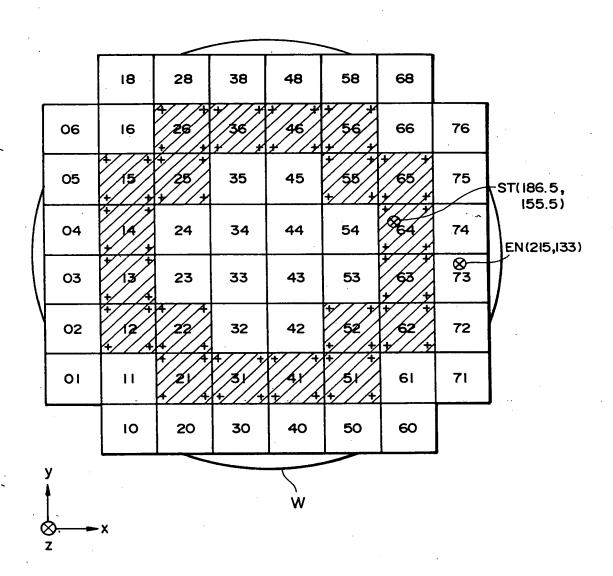




Fig. 12

Fig. 13

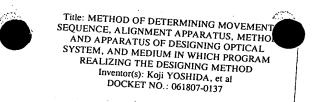


Fig. 14

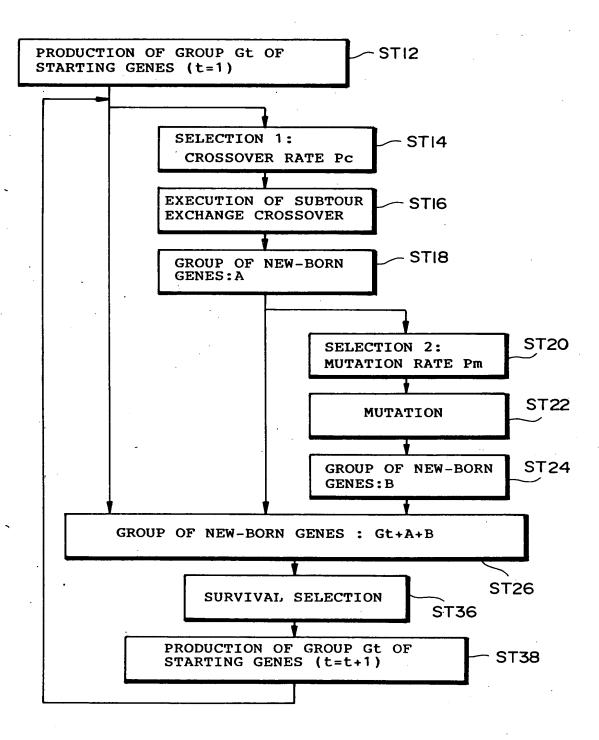


Fig. 15

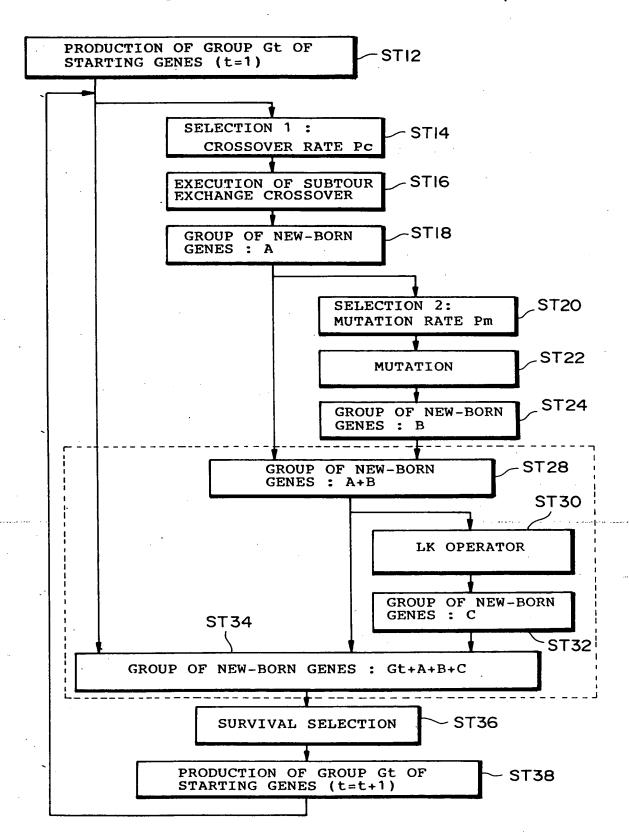




Fig. 16

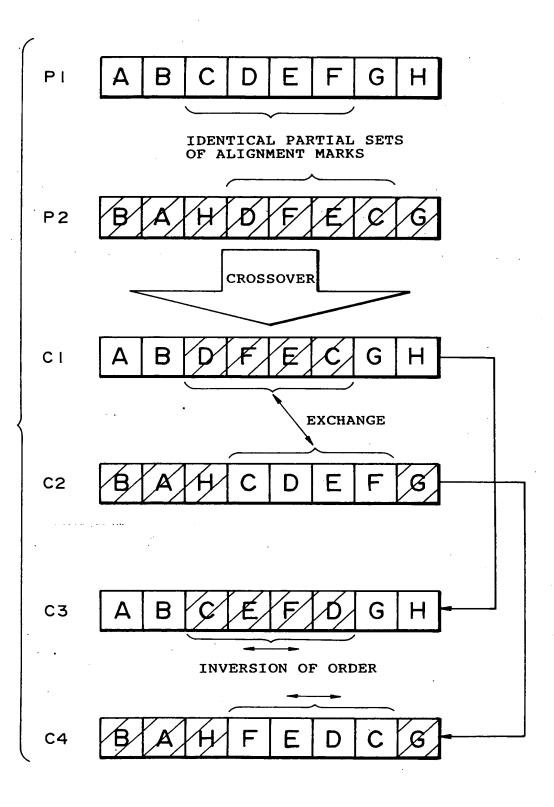




Fig. 17

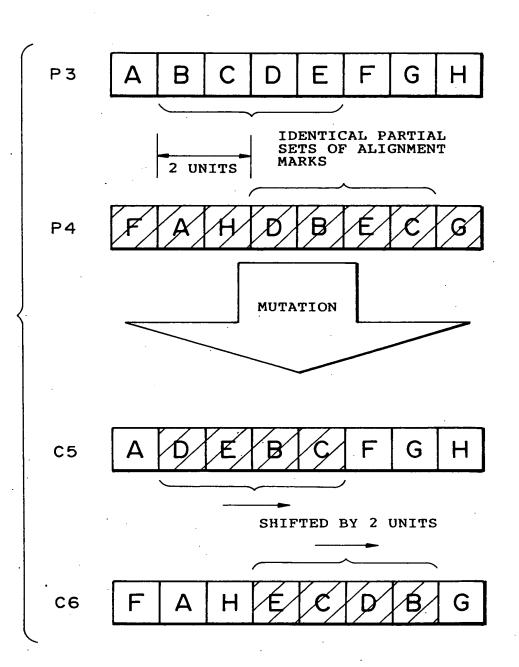




Fig. 18

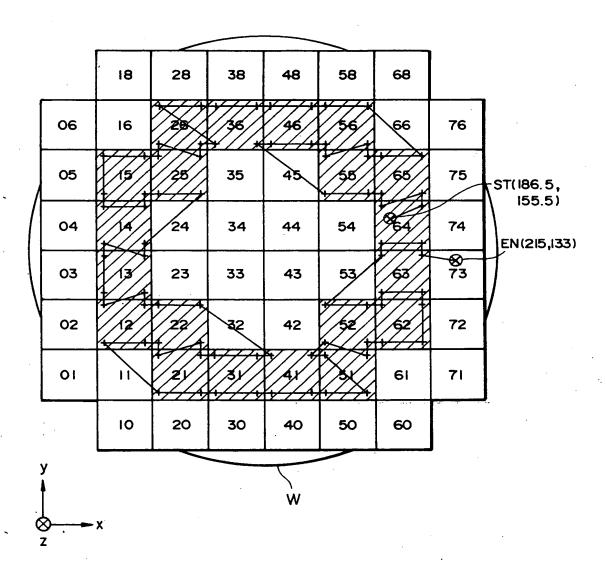




Fig. 19

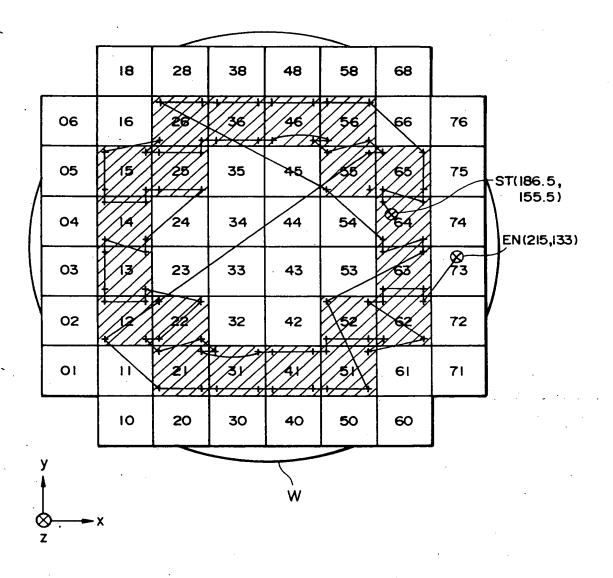




Fig.20

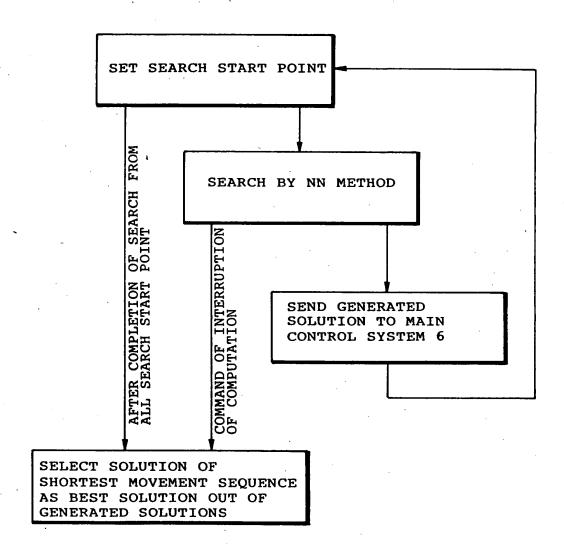




Fig.21

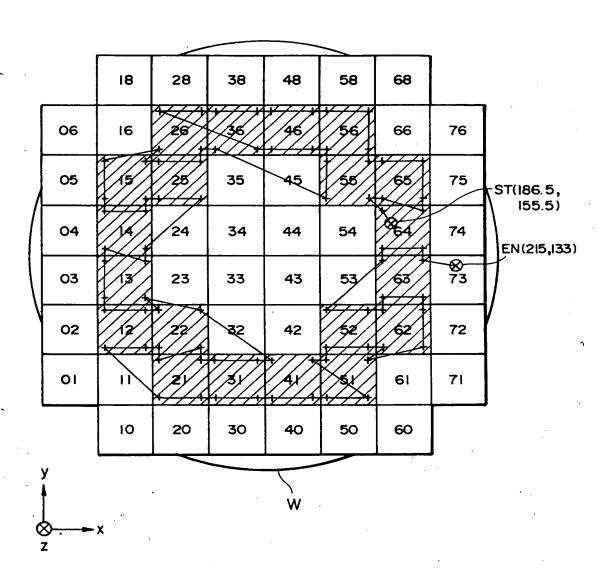
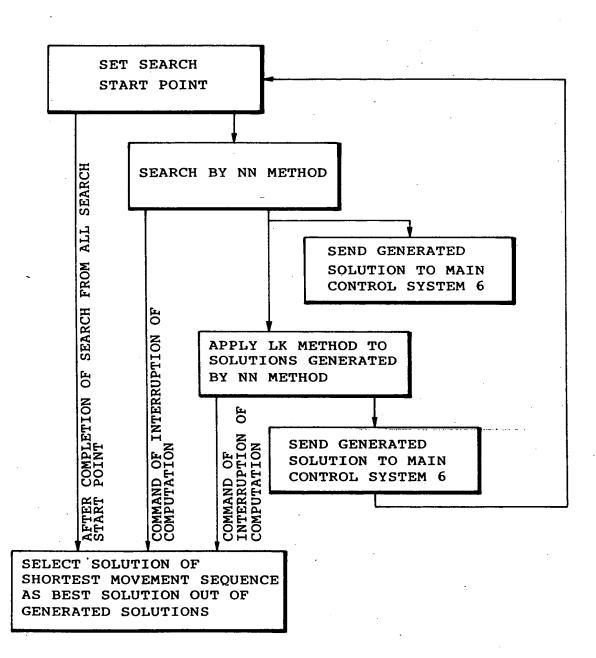




Fig.22



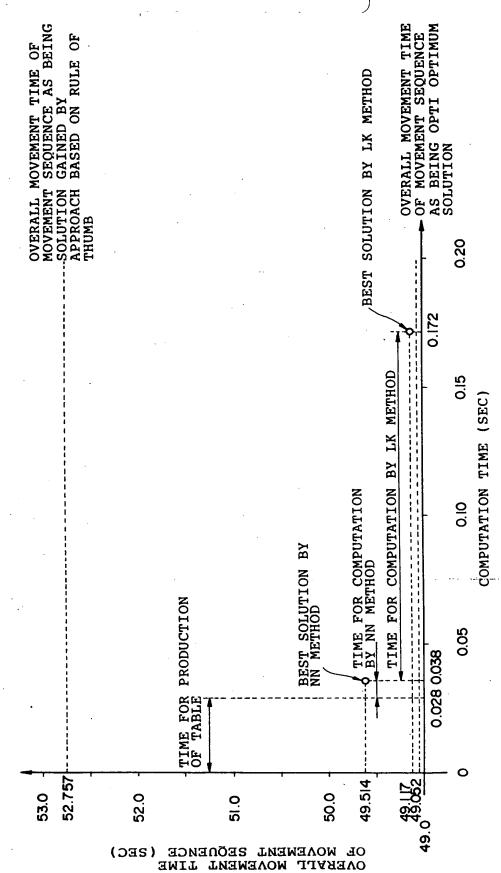
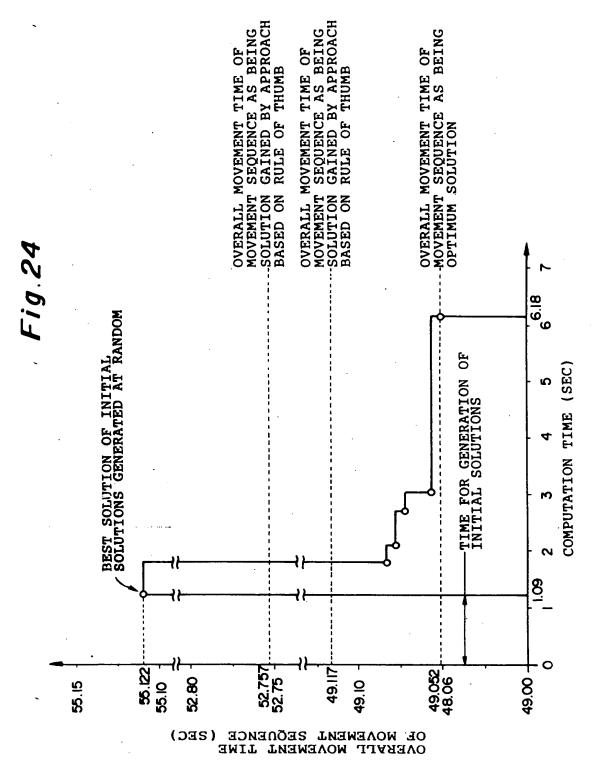


Fig. 23



MOVEMENT SEQUENCE AS BEING SOLUTION GAINED BY OF OVERALL MOVEMENT TIME OF MOVEMENT SEQUENCE AS BEING OPTIMUM SOLUTION OVERALL MOVEMENT TIME OF BASED ON RULE SOLUTION APPROACH THUMB S COMPUTATION TIME (SEC) BEST SOLUTION OF INITIAL SOLUTIONS BY NN METHOD+LK METHOD TIME FOR GENERATION OF INITIAL SOLUTIONS 0.172 49.062 49.06 52.757 52.75 49.117 52.80 49.10 WOVEMENT SEQUENCE (SEC)



Fig.26

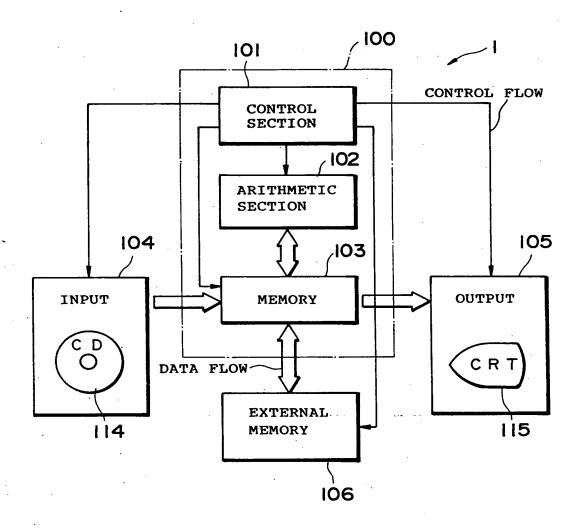




Fig. 27

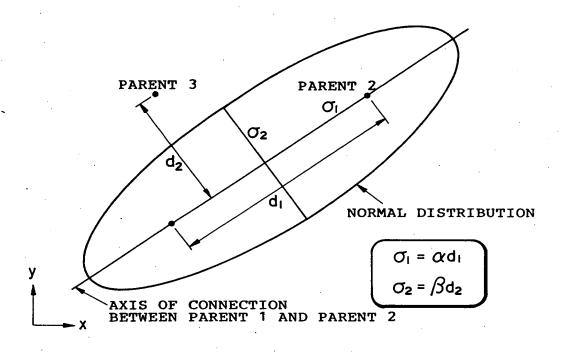


Fig. 28

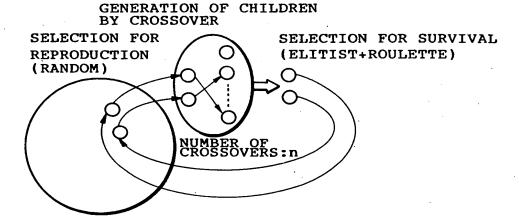




Fig.29

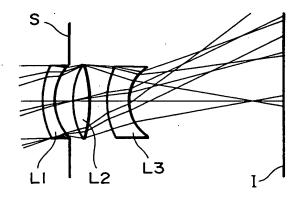
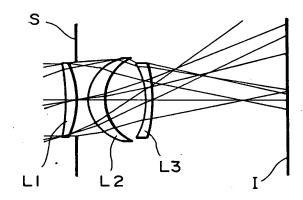
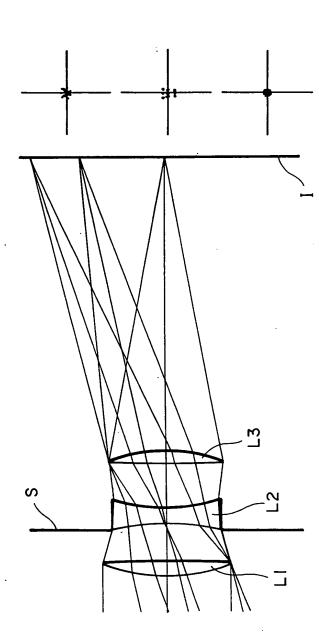


Fig. 30





Fia 31



Fig.32

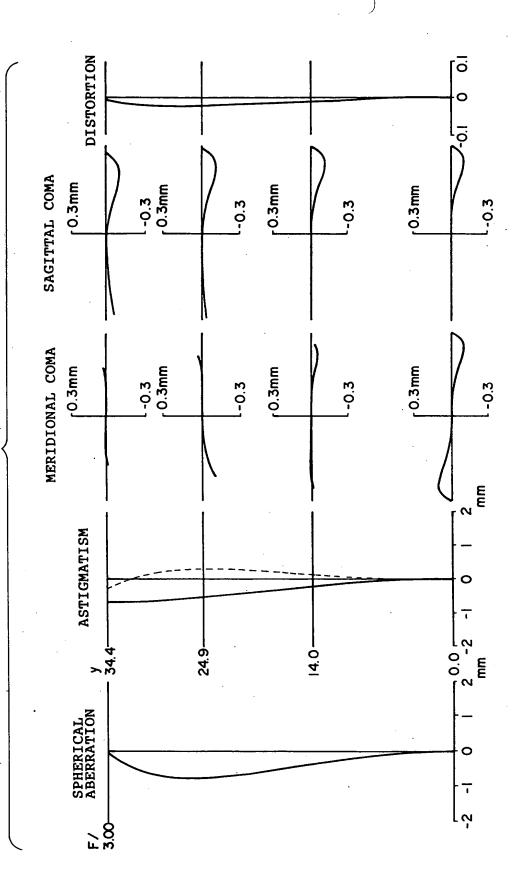




Fig. 33

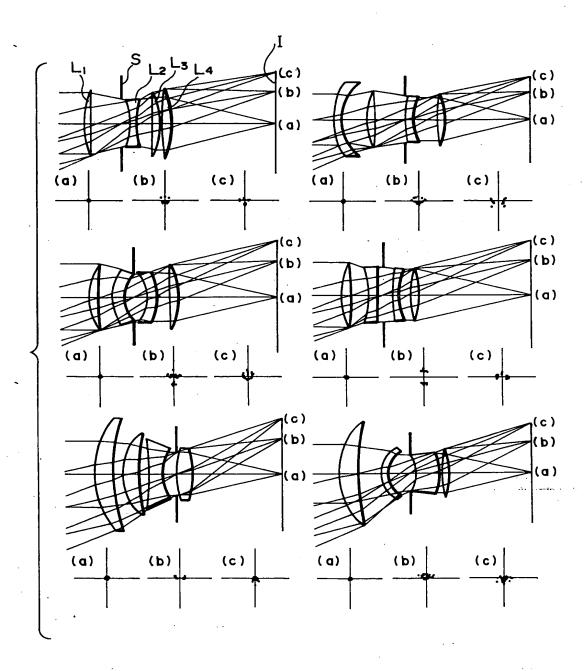
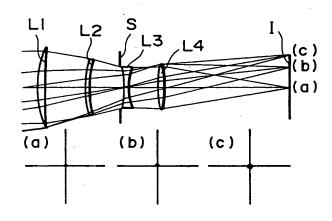




Fig.34



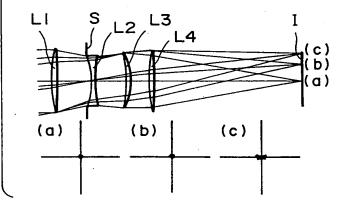
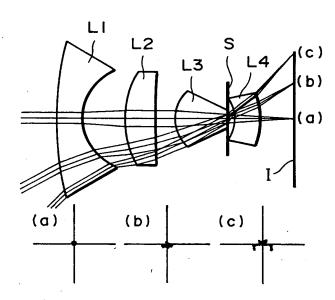




Fig. 35



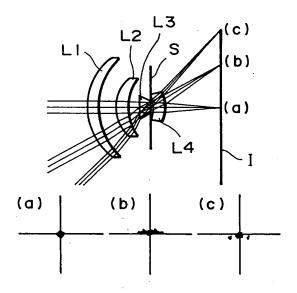
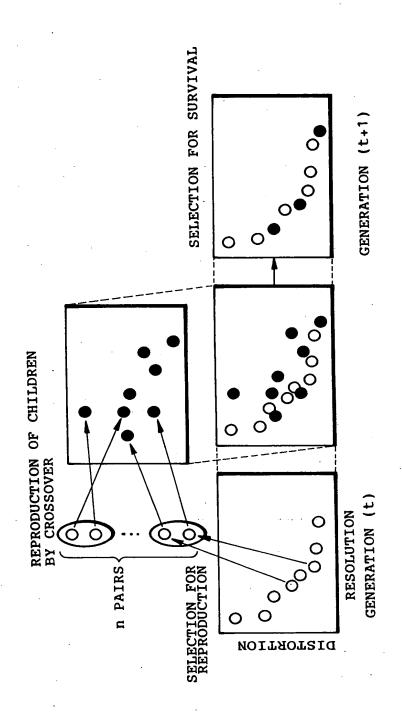
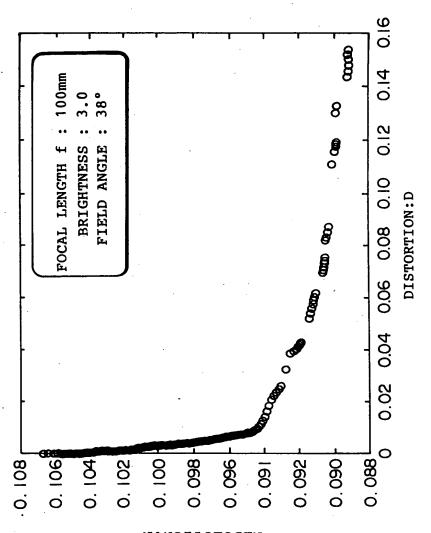




Fig. 36



Title: METHOD OF DETERMINING MOVEMENT SEQUENCE, ALIGNMENT APPARATUS, MET AND APPARATUS OF DESIGNING OPTICA SYSTEM, AND MEDIUM IN WHICH PROGRAM REALIZING THE DESIGNING METHOD Inventor(s): Koji YOSHIDA, et al DOCKET NO.: 061807-0137



KESOLUTION:R

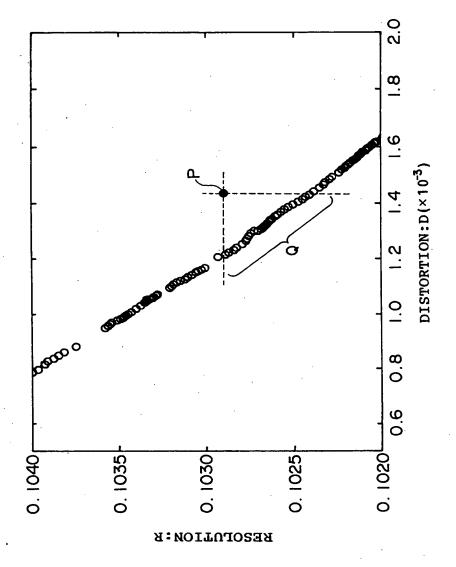


Fig. 38



Fig. 39

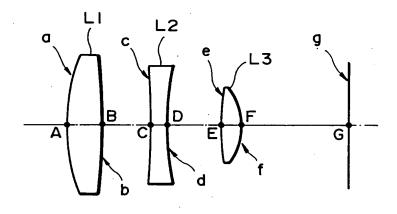


Fig. 41

GENE REPRESENTATION: Q b C

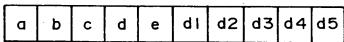
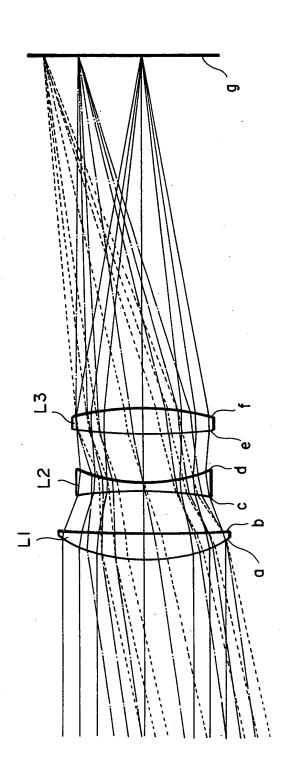




Fig. 40



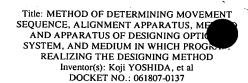


Fig. 42

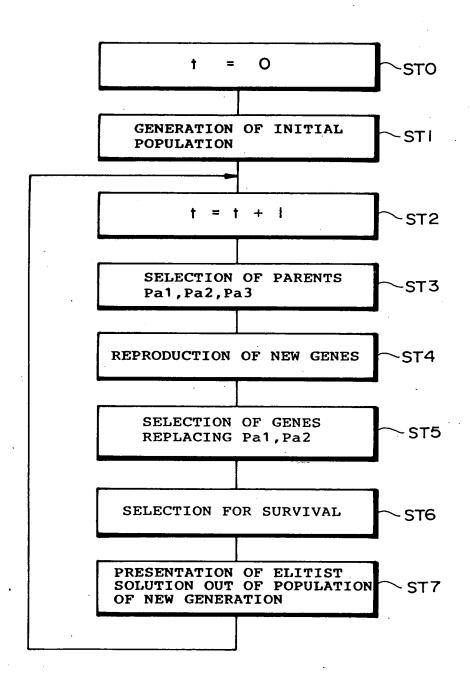
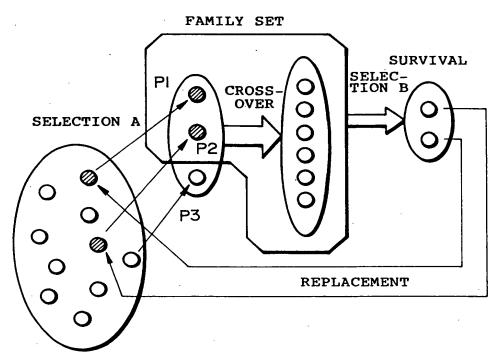




Fig. 43



GENE POPULATION



Fig. 44

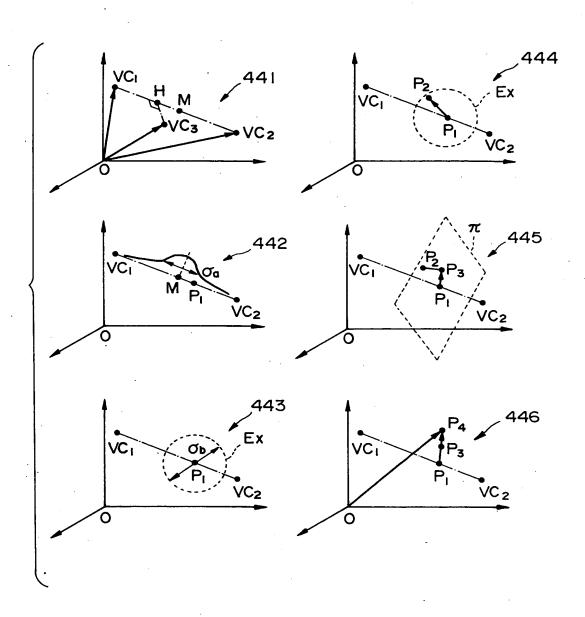




Fig. 45

